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On global solutions of the nonlinear Moore-Gibson-Thompson equation

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Abstract: This work is devoted to study the global solutions of a class of nonlinear Moore-Gibson-Thompson equation. By applying the Galerkin and compact methods, we derive some sufficient conditions on the nonlinear terms, which lead to the existence and uniqueness of the global solution.

Keywords: Moore-Gibson-Thompson equation; Initial boundary value problem; Galerkin method; Existence and uniqueness of global solution.

MSC: 35L20.

1. Introduction

The object of this work is to study the global solution to the following boundary value problem for the Moore-Gibson-Thompson equation

$$\alpha u_{ttt} + \beta u_{tt} - c^2 \Delta u - r \Delta u_t + f(u) = 0, \text{ in } \Omega \times (0, +\infty), \quad (1)$$

$$u(x, t) = 0 \text{ on } \partial\Omega, \quad (2)$$

$$u(x, 0) = u_0(x), u_t(x, 0) = u_1(x), u_{tt}(x, 0) = u_2(x), x \in \Omega, \quad (3)$$

where Ω is a bounded domain in R^n ($n \geq 1$) with sufficiently smooth boundary $\partial\Omega$, $u_0(x)$, $u_1(x)$ and $u_2(x)$ are given functions and f is a given nonlinear function. All the parameters α, β, c^2, r are assumed to be positive constants.

In recent years, increasing attention has been paid to the well-posedness and asymptotic behavior of the Moore-Gibson-Thompson (MGT) equation, see [1–7]. The MGT model is considered through third-order (in time), strictly hyperbolic partial differential equation as follows

$$\alpha u_{ttt} + \beta u_{tt} - c^2 \Delta u - r \Delta u_t = f(x), \quad (4)$$

it is one of the nonlinear acoustic models describing the propagation of acoustics wave in gases and liquid, it has a wide range of applications in medical and industry. In the physical context of the acoustic waves, u is the velocity potential of the acoustic phenomena, α denotes the thermal relaxation time, c denotes the speed of sound, β denotes friction, and b denotes a parameter of diffusivity.

It is often convenient to write MGT equation as an abstract form

$$\alpha u_{ttt} + \beta u_{tt} + c^2 Au + r Au_t = f(u, u_t, u_{tt}), \quad (5)$$

and it has been shown [8,9] that the linear part of Eq. (5) generates a strongly continuous semigroup as long as $r > 0$. In [10], the authors provided a brief overview of well-posedness results, both local and global, pertinent to various configurations of MGT equations. Especially, the authors in [11] considered the following model with nonlinear control feedback

$$\tau u_{ttt} + \alpha \beta u_{tt} + c^2 Au + b Au_t + \beta u_t^3 = 2ku_t^2 + p(u), \quad (6)$$

where the parameter $\beta > 0$, $p(u)$ denotes an active force and the operator A is strictly positive. By semigroup method, it was proved in [11] we that (6) with initial data of arbitrary size in H is locally and globally well-posed under the following assumption: $p \in C^1(R)$ and its derivative satisfies $-\delta \leq p'(s) \leq m$ for some positive constants δ and m . Kaltenbacher *et al.*, [12] established the well-posedness by Galerkin approximations and then employ fixed-point arguments for well-posedness of the Jordan-Moore-Gibson-Thompson (JMGT) equation

$$\alpha u_{ttt} + \beta u_{tt} - b\Delta u_t - c^2\Delta u = \left(\frac{1}{c^2} \frac{B}{2A} u_t^2 + |\nabla u|^2\right)_t. \tag{7}$$

More recently, Boulaaras *et al.*, [13] proved the existence and uniqueness of the weak solution of the Moore-Gibson-Thompson equation with the integral condition by applying the Galerkin method.

In this paper, we extend the results in [11] to Problem (1)-(3) by applying the Galerkin method and compact method. The contents of this paper are organized as follows; In §2, we prepare some materials needed for our proof. Finally, in §3, we give the main result and the proof.

2. Preliminaries

Throughout this paper, the domain Ω is assumed to be sufficiently smooth to admit integration by parts and second-order elliptic regularity. We use C to denote a universal positive constant that may have different values in different places. $W^{m,2}(\Omega) = H^m(\Omega)$ and $W_0^{m,2}(\Omega) = H_0^m(\Omega)$ denote the well-known Sobolev space. We denote by $\|\cdot\|_p$ the $L^p(\Omega)$ norm and by $\|\nabla \cdot\|$ the norm in $H_0^1(\Omega)$. In particular, we denote $\|\cdot\| = \|\cdot\|_2$

By a weak solution $u(x, t)$ of Problem (1)-(3) on $\Omega \times [0, T]$ for any $T > 0$, we mean $u \in L^\infty((0, T); H^2(\Omega) \cap H_0^1(\Omega)) \cap W^{1,\infty}((0, T); H_0^1(\Omega)) \cap W^{2,\infty}((0, T); L^2(\Omega))$, $\Delta u_t, u_{ttt} \in L^\infty((0, T); H^{-1}(\Omega))$ such that $u(x, 0) = u_0(x)$ a.e. in Ω , $u_t(x, 0) = u_1(x)$ a.e. in Ω , $u_{tt}(x, 0) = u_2(x)$ a.e. in Ω , and

$$\alpha(u_{ttt} + \beta u_{tt} - c^2\Delta u - r\Delta u_t + f(u), v) = 0$$

for any $v \in H_0^1(\Omega)$, a.e. $t \in [0, T]$.

In this paper, we assume $\alpha, \beta, c^2, r > 0$ and

$$f \in C^1 \text{ and } |f'(s)| \leq C_1. \tag{8}$$

Lemma 1. [14] Let $\Omega \in R^n$ be a bounded domain and w_j be a base of $L^2(\Omega)$. Then for any $\epsilon > 0$ there exist a positive constant N_ϵ , such that

$$\|u\| \leq \left(\sum_{j=1}^{N_\epsilon} (u, w_j)\right)^{\frac{1}{2}} + \epsilon \|u\|_{1,p}$$

for any $u \in W_0^{1,p}(\Omega)$ ($2 \leq p < \infty$), where N_ϵ is independent on u .

Lemma 2. [15] Let $G(z_1, z_2, \dots, z_h)$ be the function of the variables z_1, z_2, \dots, z_h and suppose that G is continuous differentiable for k -times ($k \geq 1$) with respect to every variable. Let $z_i(x, t) \in L^\infty([0, T]; H^k(\Omega))$ ($i = 1, 2, \dots, h$), then the estimation

$$\int_{\Omega} |D_x^k G(z_1(x, t), z_2(x, t), \dots, z_h(x, t))|^2 dx < C(M, k, h) \sum_{i=1}^h \|z_i\|_{H^k(\Omega)}$$

holds, where $D_x = \frac{\partial}{\partial x}$, $M = \max_{i=1,2,\dots,h} \max_{0 \leq t \leq T, x \in \Omega} |z_i(x, t)|$.

3. Solvability of the problem

In this section, by using Galerkin’s method and compactness method, we shall prove the existence of global solutions of Problem (1)-(3).

Let $\{w_j(x)\}_{j \in N}$ be the eigenfunctions of the following boundary problem

$$-\Delta w = \lambda w, x \in \Omega; w = 0, x \in \partial\Omega, \tag{9}$$

corresponding to the eigenvalue $\lambda_j(j = 1, 2, 3, \dots)$. Then $\{w_j(x)\}_{j \in \mathbb{N}}$ can be normalized to form an orthogonal basis of $H^2(\Omega) \cap H_0^1(\Omega)$ and to be orthonormal with respect to the $L^2(\Omega)$ scalar product.

Now, we seek an approximate solution of Problem (1)-(3) in the form of

$$u^N(x, t) = \sum_{j=1}^N T_{jN}(t)w_j(x), \tag{10}$$

where the constants T_{jN} are defined by the conditions $T_{jN}(t) = (u^N(x, t), w_j(x))$ and can be determined from the relation

$$\alpha(u_{ttt}^N, w_j) + \beta(u_{tt}^N, w_j) - c^2(\Delta u^N, w_j) - r(\Delta u_t^N, w_j) + (f(u^N), w_j) = 0, \tag{11}$$

$$(u^N(0), w_j) = (u_0, w_j) = u_{0j}, (u_t^N(0), w_j) = (u_1, w_j) = u_{1j}, (u_{tt}^N(0), w_j) = (u_2, w_j) = u_{2j}. \tag{12}$$

Lemma 3. Assume (8) holds, $u_0 \in H^2(\Omega) \cap H_0^1(\Omega)$, $u_1 \in H_0^1(\Omega)$, and $u_2 \in L^2(\Omega)$, then for any $T > 0$, Problem (11)-(12) possesses a solution u^N on $[0, T]$, and the following estimate holds in the class

$$\|u^N\|^2 + \|u_t^N\|^2 + \|\nabla u^N\|^2 + \alpha \|u_{tt}^N\|^2 + r \|\nabla u_t^N\|^2 + \int_0^t \|\nabla u_t^N\|^2 d\tau + \beta \|\nabla u_{tt}^N\|^2 d\tau \leq C. \tag{13}$$

Proof. Problem (11)-(12) leads to a system of ODEs for unknown functions $T_{jN}(t)$. Based on standard existence theory for ODE, one can obtain functions $T_{jN}(t) : [0, t_k] \rightarrow \mathbb{R}, j = 1, 2, \dots, k$, which satisfy approximate Problem (11)-(12) in a maximal interval $[0, t_k], t_k \in (0, T]$. This solution is then extended to the closed interval $[0, T]$ by using the estimate below.

Multiplying (11) by $T_{jNtt}(t)$, summing up the products for $j = 1, 2, \dots, N$ and integrating by parts, we get

$$\alpha(u_{ttt}^N, u_{tt}^N) + \beta(u_{tt}^N, u_{tt}^N) + c^2(\nabla u^N, \nabla u_{tt}^N) + r(\nabla u_t^N, \nabla u_{tt}^N) + (f(u^N), u_{tt}^N) = 0. \tag{14}$$

Integrating (14) with respect to t from 0 to t , we obtain

$$\begin{aligned} &\alpha \|u_{tt}^N\|^2 + 2\beta \int_0^t \|u_{tt}^N\|^2 d\tau + r \|\nabla u_t^N\|^2 + 2 \int_0^t (f(u^N), u_{tt}^N) d\tau \\ &= -c^2 \int_0^t (\nabla u^N, \nabla u_{tt}^N) d\tau + \alpha \|u_{tt}^N(0)\|^2 + r \|\nabla u_t^N(0)\|^2. \end{aligned} \tag{15}$$

We observe that

$$\int_0^t (f(u^N), u_{tt}^N) d\tau = (f(u^N), u_{tt}^N)|_0^t - \int_0^t \int_{\Omega} f'(u^N)(u_t^N)^2 dx d\tau \tag{16}$$

and

$$\int_0^t (\nabla u^N, \nabla u_{tt}^N) d\tau = (\nabla u^N, \nabla u_t^N)|_0^t - \int_0^t \|\nabla u_t^N\|^2 d\tau. \tag{17}$$

Adding $2[(u^N, u_t^N) + (u_t^N, u_{tt}^N) + (\nabla u^N, \nabla u_t^N)]$ to both sides of (15) and a substitution of the equalities (16) and (17) in (15) gives

$$\begin{aligned} &\frac{d}{dt} [\|u^N\|^2 + \|u_t^N\|^2 + \|\nabla u^N\|^2] + \alpha \|u_{tt}^N\|^2 + 2\beta \int_0^t \|u_{tt}^N\|^2 d\tau + r \|\nabla u_t^N\|^2 \\ &= 2[(u^N, u_t^N) + (u_t^N, u_{tt}^N) + (\nabla u^N, \nabla u_t^N)] + \alpha \|u_{tt}^N(0)\|^2 + r \|\nabla u_t^N(0)\|^2 - 2(f(u^N), u_{tt}^N)|_0^t \\ &\quad + 2 \int_0^t \int_{\Omega} f'(u^N)(u_t^N)^2 dx d\tau - 2c^2(\nabla u^N, \nabla u_t^N)|_0^t + 2c^2 \int_0^t \|\nabla u_t^N\|^2 d\tau. \end{aligned} \tag{18}$$

Then, by Hölder inequality and the fact $|f(s)| = |\int_0^t f'(s) ds| \leq C_1|s|$ by (A1), we arrive at

$$\begin{aligned}
 & \frac{d}{dt} [\|u^N\|^2 + \|u_t^N\|^2 + \|\nabla u^N\|^2] + \alpha \|u_{tt}^N\|^2 + 2\beta \int_0^t \|u_{tt}^N\|^2 d\tau + r \|\nabla u_t^N\|^2 \\
 & \leq 2 \|u^N\| \|u_t^N\| + 2 \|u_t^N\| \|u_{tt}^N\| + 2 \|\nabla u^N\| \|\nabla u_t^N\| + \alpha \|u_{tt}^N(0)\|^2 + r \|\nabla u_t^N(0)\|^2 \\
 & \quad + 2C_1 \|u^N\| \|u_t^N\| + 2C_1 \|u^N(0)\| \|u_t^N(0)\| + 2C_1 \int_0^t \|u_t^N\|^2 d\tau \\
 & \quad + 2c^2 \|\nabla u^N\| \|\nabla u_t^N\| + 2c^2 \|\nabla u^N(0)\| \|\nabla u_t^N(0)\| + 2c^2 \int_0^t \|\nabla u_t^N\|^2 d\tau \\
 & \leq \frac{1}{2} (\alpha \|u_{tt}^N\|^2 + r \|\nabla u_t^N\|^2) + C_2 (\|u^N\|^2 + \|u_t^N\|^2 + \|\nabla u^N\|^2) \\
 & \quad + 2C_1 \int_0^t \|u_t^N\|^2 d\tau + 2c^2 \int_0^t \|\nabla u_t^N\|^2 d\tau + \alpha \|u_{tt}^N(0)\|^2 + r \|\nabla u_t^N(0)\|^2 \\
 & \quad + C_3 \|u^N(0)\|^2 + C_4 \|u_t^N(0)\|^2 + c^2 \|\nabla u^N(0)\|^2 + c^2 \|\nabla u_t^N(0)\|^2. \tag{19}
 \end{aligned}$$

Taking into account that

$$\|u_{tt}^N(0)\|^2 + \|\nabla u_t^N(0)\|^2 + \|\nabla u^N(0)\|^2 \rightarrow \|u_2\|^2 + \|\nabla u_0\|^2 + \|\nabla u_1\|^2$$

and

$$\|u^N(0)\|^2 + \|u_t^N(0)\|^2 \rightarrow \|u_0\|^2 + \|u_1\|^2$$

as $N \rightarrow \infty$, then applying the Gronwall inequality to (19) and then integrating from 0 to t appears that

$$\|u^N\|^2 + \|u_t^N\|^2 + \|\nabla u^N\|^2 + \alpha \|u_{tt}^N\|^2 + r \|\nabla u_t^N\|^2 + \int_0^t \|\nabla u_t^N\|^2 d\tau + \beta \|\nabla u_{tt}^N\|^2 d\tau \leq C. \tag{20}$$

Multiplying (11) by $\lambda_j T_{jN}(t)$ summing up the products for $j = 1, 2, \dots, N$, integrating by parts and integrating with respect to t , we get

$$r \|\Delta u^N\|^2 + c^2 \int_0^t \|\Delta u^N\|^2 d\tau = 2\alpha \int_0^t (u_{ttt}^N, \Delta u^N) d\tau + 2\beta \int_0^t (u_{tt}^N, \Delta u^N) d\tau + \int_0^t (f(u^N), \Delta u^N) d\tau + r \|\Delta u^N(0)\|^2. \tag{21}$$

Combining Cauchy inequality, the fact $\|\Delta u^N(0)\|^2 \rightarrow \|\Delta u_0\|^2$, and $|f(s)| \leq C_1|s|$, and making use of the following inequality

$$\begin{aligned}
 \int_0^t (u_{ttt}^N, \Delta u^N) d\tau &= (u_{ttt}^N, \Delta u^N)|_0^t - \int_0^t (u_{tt}^N, \Delta u_t^N) d\tau \\
 &= (u_{ttt}^N, \Delta u^N) - (u_{tt}^N(0), \Delta u^N(0)) + \frac{1}{2} \|\nabla u_t^N\|^2 - \frac{1}{2} \|\nabla u_t^N(0)\|^2,
 \end{aligned}$$

we have

$$\begin{aligned}
 & r \|\Delta u^N\|^2 + c^2 \int_0^t \|\Delta u^N\|^2 d\tau \\
 & \leq 2\alpha \|u_{tt}^N\| \|\Delta u^N\| + 2\alpha \|u_{tt}^N(0)\| \|\Delta u^N(0)\| + \alpha (\|\nabla u_t^N\|^2 - \|\nabla u_t^N(0)\|^2) + 2\beta \int_0^t \|u_{tt}^N\| \|\Delta u^N\| d\tau \\
 & \quad + \int_0^t \|f(u^N)\| \|\Delta u^N\| d\tau + r \|\Delta u^N(0)\|^2 \\
 & \leq \epsilon_1 \|\Delta u^N\|^2 + C_6 (\|u_{tt}^N\|^2 + \|\nabla u_t^N\|^2) + C_7 (\|u_{tt}^N(0)\|^2 + \|\Delta u^N(0)\|^2 + \|\nabla u_t^N(0)\|^2) \\
 & \quad + \epsilon_1 \int_0^t \|\Delta u^N\|^2 d\tau + C_8 \int_0^t \|u_{tt}^N\|^2 d\tau + C_9 \int_0^t \|u^N\|^2 d\tau. \tag{22}
 \end{aligned}$$

Choosing ϵ_1 sufficiently small and ϵ_2 sufficiently large such that $\epsilon_2 > 2c^2$, then it follows from (22) and (20) that

$$\|\Delta u^N\|^2 \leq C_{10} \int_0^t \|\Delta u^N\|^2 d\tau + C_{11}. \tag{23}$$

Thus, applying Gronwall’s inequality to (23), we deduce

$$\|\Delta u^N\|^2 \leq C. \tag{24}$$

Combining (20) and (24), we get

$$\|u^N\|^2 + \|u_t^N\|^2 + \|\nabla u^N\|^2 + \|u_{tt}^N\|^2 + \|\nabla u_t^N\|^2 + \int_0^t \|\nabla u_t^N\|^2 d\tau + \beta \|\nabla u_{tt}^N\|^2 d\tau \leq C. \tag{25}$$

Furthermore, by (25), we have that (11)-(12) possesses a global solution. \square

Theorem 1. Assume (8) holds, $u_0 \in H^2(\Omega) \cap H_0^1(\Omega)$, $u_1 \in H_0^1(\Omega)$, and $u_2 \in L^2(\Omega)$, then for any $T > 0$, Problem (1)-(3) possesses a unique global solution.

Proof. For any $v \in H_0^1(\Omega)$, it follows that

$$\alpha |(u_{ttt}^N, v)| \leq (\beta \|u_{tt}^N\| + c^2 \|\Delta u^N\| + \|\nabla u_t^N\| + C_1 \|u^N\|) \|v\|_{H_0^1}. \tag{26}$$

Thus, using Lemma 3, it follows that

$$\|u_{ttt}^N\|_{H^{-1}(\Omega)} \leq M. \tag{27}$$

Similarly, we have

$$\|\Delta u_t^N\|_{H^{-1}(\Omega)} \leq M. \tag{28}$$

From Lemma 3, (27) and (28), there exist a subsequence of $\{u^N\}$, still denoted by $\{u^N\}$, and a function u, ξ, η , such that

$$u^N \rightarrow u \text{ weak } * \text{ in } L^\infty(0, T, H^2(\Omega) \cap H_0^1(\Omega)), \tag{29}$$

$$u_t^N \rightarrow u_t \text{ weak } * \text{ in } L^\infty(0, T, H_0^1(\Omega)), \tag{30}$$

$$u_{tt}^N \rightarrow u_{tt} \text{ weak } * \text{ in } L^\infty(0, T, L^2(\Omega)), \tag{31}$$

$$u_{ttt}^N \rightarrow u_{ttt} \text{ weak } * \text{ in } L^\infty(0, T, H^{-1}(\Omega)), \tag{32}$$

$$f(u^N) \rightarrow \xi \text{ weak } * \text{ in } L^\infty(0, T, H^{-1}(\Omega)), \tag{33}$$

$$\Delta u_t^N \rightarrow \eta \text{ weak } * \text{ in } L^\infty(0, T, H^{-1}(\Omega)). \tag{34}$$

and for any $t \in [0, T]$

$$u^N \rightarrow u \text{ weakly in } H^2(\Omega) \cap H_0^1(\Omega), \tag{35}$$

$$u_t^N \rightarrow u_t \text{ weakly in } H_0^1(\Omega), \tag{36}$$

$$u_{tt}^N \rightarrow u_{tt} \text{ weakly in } L^2(\Omega), \tag{37}$$

$$u_{ttt}^N \rightarrow u_{ttt} \text{ weakly in } H^{-1}(\Omega), \tag{38}$$

$$f(u^N) \rightarrow \xi \text{ weak } * \text{ in } H^{-1}(\Omega), \tag{39}$$

$$\Delta u_t^N \rightarrow \eta \text{ weak } * \text{ in } H^{-1}(\Omega). \tag{40}$$

Since $f \in C^1$ and $\|f(u^N)\| \leq C \|u^N\| \leq C$, for any $v \in H_0^1(\Omega)$ and any $t \in [0, T]$, we have

$$(\Delta u_t^N, v) = -(\nabla u_t^N, \nabla v) \rightarrow -(\nabla u_t, \nabla v) = (\Delta u_t, v), \tag{41}$$

$$f(u^N) \rightarrow f(u) \tag{42}$$

as $N \rightarrow \infty$. Then we get $\xi = f(u), \eta = \nabla u_t$, combining this with (35)-(40), we have

$$u \in L^\infty((0, T); H^2(\Omega) \cap H_0^1(\Omega)) \cap W^{1,\infty}((0, T); H_0^1(\Omega)) \cap W^{2,\infty}((0, T); L^2(\Omega)),$$

$$\Delta u_t, u_{ttt} \in L^\infty((0, T); H^{-1}(\Omega)).$$

By using Lemma 3 and (27), we observe that

$$|(u^N, w_j)| + \sum_{k=1}^3 |(u_{tk}^N, w_j)| \leq M, \tag{43}$$

where $u_{tk}^N = \frac{\partial^k u^N}{\partial t^k}$. Then, by Ascoli-Arcela theorem, we can select from $\{u^N\}$ a subsequence, still denoted by $\{u^N\}$, such that as $N \rightarrow \infty$, the subsequence

$$(u^N, w_j) \rightarrow (u, w_j), (u_{tk}^N, w_j) \rightarrow (u_{tk}, w_j), k = 1, 2, 3, j = 1, 2, \dots \tag{44}$$

In particular, we take $t = 0$ and we note that $\{w_j(x)\}_{j \in \mathbb{N}}$ are an orthogonal basis of $L^2(\Omega)$, we know that

$$u(x, 0) = u_0(x), u_t(x, 0) = u_1(x), u_{tt}(x, 0) = u_2(x) \text{ a.e. in } \Omega. \tag{45}$$

By (29)-(34),(44) and Lemma 2.1, we have

$$u^N \rightarrow u, u_t^N \rightarrow u_t \text{ in } C([0, T], L^2(\Omega)). \tag{46}$$

Thanks to (29)-(42), letting $N \rightarrow \infty$ in (11), leads to

$$\alpha(u_{ttt}, v) + \beta(u_{tt}, v) - c^2(\Delta u, v) - r(\Delta u_t, v) + (f(u), v) = 0 \tag{47}$$

for any $v \in H_0^1(\Omega)$. Altogether, we conclude that u is a solution of the initial boundary Problem (1)-(3).

Now, suppose that there exist two different solutions u_1, u_2 for Problem (1)-(3), then the difference $w = u_1 - u_2$ satisfies

$$\alpha w_{ttt} + \beta w_{tt} - c^2 \Delta w - r \Delta w_t + f(u_1) - f(u_2) = 0, \text{ in } \Omega \times (0, +\infty), \tag{48}$$

$$w(x, t) = 0 \text{ on } \partial\Omega, \tag{49}$$

$$w(x, 0) = 0, w_t(x, 0) = 0, w_{tt}(x, 0) = 0, x \in \Omega, \tag{50}$$

Integrating (48) for t from 0 to t , we have

$$\alpha w_{tt} + \beta w_t - r \Delta w = \int_0^t (c^2 \Delta w + f(u_2) - f(u_1)) d\tau. \tag{51}$$

Multiplying the Eq. (51) by w_t , integrating over Ω , adding up (w, w_t) , we obtain

$$\begin{aligned} \frac{1}{2}(\alpha \|w_t\|^2 + r \|\nabla w\|^2 + \|w\|^2) + \beta \|w_t\|^2 &= 2 \int_0^t (c^2 \Delta w + f(u_2) - f(u_1)) w_t d\tau \\ &= 2c^2(\|\nabla w\|^2 - \|\nabla w_0\|^2) + 2 \int_0^t \int_\Omega \theta w w_t dx d\tau \\ &\leq C(\|\nabla w\|^2 + \|w_t\|^2), \end{aligned} \tag{52}$$

where we have used mean value theorem and $|\theta| \leq 1$. By applying Gronwall inequality, we deduce that

$$\alpha \|w_t\|^2 + r \|\nabla w\|^2 + \|w\|^2 = 0. \tag{53}$$

This implies that $w = 0$ for all $t \in [0, T]$. Thus the uniqueness is proved. \square

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