



# Article **Characterization of a vector measure: application in the** $GL(2; \mathbb{R})$ group

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**Abstract:** In this paper we characterize a bounded vector measure on Lie compact group  $G = GL(2; \mathbb{R})$ . It is a question of considering a bounded vector measure *m* defined from K(G; E) the space of *E* valued functions with compact support on *G* and giving its integral form.

Keywords: Vector measure, Haar measure, Lie compact group, absolute continuity.

# 1. Introduction

n 1989, Assiamoua [1] worked on the properties of vector measure, introduced by Diestel in [2]. In 2013, Awussi [3] proved that any bounded vector measure is absolutely continue with respect to Haar measure. In 2013, Mensah [4] worked on Fourier-Stieljes transform of vector measures on compact groups.

In this paper, we treat with a special case by giving a form to a bounded vector measure on  $G = GL(2; \mathbb{R})$ . We consider a vector measure which is absolutely continue with respect to Haar measure and then give the integral form [5] to this vector measure. The first essential part of our work is to establish the form of Haar measure on  $G = GL(2; \mathbb{R})$ . We prove that

$$\mu(f) = \int_{\mathbb{R}^4} \frac{f(x_{11}; x_{12}; x_{21}; x_{22})}{(x_{11}x_{22} - x_{12}x_{21})^2} dx_{11} dx_{12} dx_{21} dx_{22};$$

 $\forall f \in K(G; E) \text{ and } x = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \in GL(2; \mathbb{R}); \text{ is a Haar measure on } G = GL(2; \mathbb{R}). \text{ Once this}$ 

demonstration achieved we go straight to generalize the form of a vector measure on  $K(GL(2; \mathbb{R}); \mathbb{R}^4)$ .

This paper is organized as follows: in Section 2, we give some definitions related to vector measure and matrices and prove the fundamental theorem which will help us in proving our main result and in Section 3 we present our main result.

# 2. Preliminaries

In this section, we give basic definitions and concepts concerning with vector measure and Lie groups.

**Definition 1.** [2] Let *G* be a locally compact group and K(G; E) be the space of *E* valued functions with compact support on *G*. A vector measure on *G* with respect to Banach spaces *E* and *F* is a linear map:

$$m: K(G; E) \to F$$
$$f \mapsto m(f)$$

such as  $\forall K$  compact in  $G \exists a_K > 0$ ,  $||m(f)||_F \le a_K ||f||_\infty$ . Where  $||.||_F$  is the norm on Banach spaces F and  $||f||_\infty = \sup\{||f(t)||_E, t \in G\}$  is the norm on K(G; E).

The value m(f) of m in  $f \in K(G; E)$  is called integral of f with respect to m and can be written as [5,6]:

$$\int_G f(t)dm(t) = m(f).$$

We consider  $GL(2;\mathbb{R})$  is the set of matrices of order two with real coefficients whose determinant is not equal to zero, *i.e.*,

$$GL(2;\mathbb{R}) = \left\{ g = \left( \begin{array}{cc} g_{11} & g_{12} \\ g_{21} & g_{22} \end{array} \right); g_{ij} \in \mathbb{R}; 1 \leq i, j \leq 2 | detg \neq 0 \right\}.$$

 $G = GL(2;\mathbb{R})$  is a Lie group. Also *G* is a manifold such that, at any point  $g \in G$ , there exists an open  $V_g$  of *G*, an open  $U_g$  of  $\mathbb{R}^4$  and  $\varphi_g$  a diffeomorphism of  $V_g$  in  $U_g$ . So each  $x = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \in GL(2;\mathbb{R})$  is assimilated to  $(x_{11}; x_{12}; x_{21}; x_{22})$  of  $\mathbb{R}^4$ .

In order to prove our main result, first we prove following fundamental theorem which allow us to get our final result. The following theorem gives us Haar's measure on  $GL(2; \mathbb{R})$ .

**Theorem 1.** Let K(G; E) be the space of E valued functions with compact support on G, where  $G = GL(2; \mathbb{R})$  and  $E = \mathbb{R}^4$ . Then  $\mu : K(G; E) \to \mathbb{R}^+$  defined as

$$\mu(f) = \int_{\mathbb{R}^4} \frac{f(x_{11}; x_{12}; x_{21}; x_{22})}{(x_{11}x_{22} - x_{12}x_{21})^2} dx_{11} dx_{12} dx_{21} dx_{22};$$
(1)

 $\forall f \in K(G; E) \text{ and } x = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \in GL(2; \mathbb{R}) \text{ is a Haar measure on } G = GL(2; \mathbb{R}).$ 

**Proof.** If  $\mu$  is a Haar measure on  $G = GL(2; \mathbb{R})$  then  $d\mu(x) = \frac{1}{(detx)^2} dx$ ,  $\forall x \in G$ . As

$$d\mu(x) = \frac{1}{(x_{11}x_{22} - x_{12}x_{21})^2} dx_{11} dx_{12} dx_{21} dx_{22}.$$

Since  $\mu(f) = \int_G f(x)d\mu(x)$ ,  $\forall f \in K(G; E)$ , we get:

$$\mu(f) = \int_{\mathbb{R}^4} \frac{f(x_{11}; x_{12}; x_{21}; x_{22})}{(x_{11}x_{22} - x_{12}x_{21})^2} dx_{11} dx_{12} dx_{21} dx_{22};$$
<sup>(2)</sup>

Conversely if  $\mu$  is a Haar measure on  $G = GL(2; \mathbb{R})$  then we have [6]:

$$\mu(f) = \int_{G} f(x) |J(L_x)|^{-1} dx \quad \forall f \in K(G; E)$$
(3)

The translation on the left  $L_x : y \mapsto xy \quad x; y \in G = GL(2; \mathbb{R})$ 

$$L_{x}(y) = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \begin{pmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{pmatrix} = \begin{pmatrix} x_{11}y_{11} + x_{12}y_{21} & x_{11}y_{12} + x_{12}y_{22} \\ x_{21}y_{11} + x_{22}y_{21} & x_{21}y_{12} + x_{22}y_{22} \end{pmatrix}$$
$$L_{x}(y) = (x_{11}y_{11} + x_{12}y_{21}; x_{11}y_{12} + x_{12}y_{22}; x_{21}y_{11} + x_{22}y_{21}; x_{21}y_{12} + x_{22}y_{22})$$
$$J(L_{x}) = \frac{dL}{dy} = \begin{pmatrix} x_{11} & 0 & x_{12} & 0 \\ 0 & x_{11} & 0 & x_{12} \\ x_{21} & 0 & x_{22} & 0 \\ 0 & x_{21} & 0 & x_{22} \end{pmatrix}$$

The Jacobian gives:

$$|J(L_x)| = \left|\frac{dL}{dy}\right| = x_{11} \begin{vmatrix} x_{11} & 0 & x_{12} \\ 0 & x_{22} & 0 \\ x_{21} & 0 & x_{22} \end{vmatrix} + x_{12} \begin{vmatrix} 0 & x_{11} & x_{12} \\ x_{21} & 0 & 0 \\ 0 & x_{21} & x_{22} \end{vmatrix}$$

$$|J(L_x)| = \left|\frac{dL}{dy}\right| = (x_{11}x_{22})^2 - x_{11}x_{12}x_{21}x_{22} - x_{11}x_{12}x_{21}x_{22} + (x_{12}x_{21})^2$$
  
=  $(x_{11}x_{22})^2 - 2x_{11}x_{12}x_{21}x_{22} + (x_{12}x_{21})^2$   
=  $(x_{11}x_{22} - x_{21}x_{12})^2$   
=  $(det x)^2$ 

According to the relationship (3) we have:

$$\begin{split} u(f) &= \int_{G} f(x) |J(L_{x})|^{-1} dx \quad \forall f \in K(G; E) \quad x \in G \\ &= \int_{G} f(x) \left( (det \, x)^{2} \right)^{-1} dx \\ &= \int_{G} \frac{f(x)}{(det \, x)^{2}} dx \\ &= \int_{\mathbb{R}^{4}} \frac{f(x_{11}; x_{12}; x_{21}; x_{22})}{(x_{11}x_{22} - x_{12}x_{21})^{2}} dx_{11} dx_{12} dx_{21} dx_{22}; \end{split}$$

The last form of  $\mu$  is a 4 linear, alternating, positive, finite, left-invariant form so it is a Haar measure on  $GL(2; \mathbb{R})$ .

The following theorem is of a capital importance.

**Theorem 2.** Let *m* be a bounded vector measure on compact Lie group G and E and F two Banach spaces. If *m* is a continuous alternating linear form in  $L^p(G; E)$  then *m* is absolutely continuous.

The following theorems are important, because once we establish the form of the Haar measure on *G*, it will be easy to establish a vector measure on K(G; E).

**Theorem 3.** [3] Let *G* be a compact group, *m* be a bounded vector measure on *G* and *p* and *q* are two conjugates numbers with  $p \ge 1$ . Then the following two assertions are equivalent:

∀h ∈ L<sup>p</sup>(G; E), m \* h ∈ C(G; E),
 ∃ f ∈ L<sup>q</sup>(G; E) such as m = fµ.

**Theorem 4.** [3] Let  $\mu$  be a Haar measure on compact Lie group G,  $p \in [1, \infty[$  and q conjugate of p. If  $\phi$  is a linear continuous form on  $L^p(G; E)$  then there exists a map  $f \in L^q(G, E)$  such as for any  $g \in L^p$ , we have  $\phi(g) = \int_G gf d\mu$ .

We use the duality theorem for p = 1 and  $q = \infty$ .

### 3. Main result

In this section, we give our main result.

**Theorem 5.** Let K(G; E) be the space of E valued functions with compact support on G, where  $G = GL(2; \mathbb{R})$  and  $E = \mathbb{R}^4$ . If m is a vector measure on K(G; E), then

$$m(f) = \int_{\mathbb{R}^4} \frac{g(x_{11}; x_{12}; x_{21}; x_{22}) f(x_{11}; x_{12}; x_{21}; x_{22})}{(x_{11}x_{22} - x_{12}x_{21})^2} dx_{11} dx_{12} dx_{21} dx_{22};$$
(4)  
$$\forall \quad f \in K(GL(2; \mathbb{R}); \mathbb{R}^4), \quad g \in L^{\infty}(GL(2; \mathbb{R}); \mathbb{R}^4), \quad x \in GL(2; \mathbb{R})$$

**Proof.** Since *m* being a vector measure on  $K(GL(2; \mathbb{R}); \mathbb{R}^4)$ , so *m* is continuous, alternating and bounded linear form. Using Theorem 2, we get  $m \ll \mu$ .

The Theorems 3 and 4 allow us to write  $dm = gd\mu$ ;  $g \in L^{\infty}(GL(2;\mathbb{R}))$ , which implies

$$dm(x) = \frac{g(x)}{(detx)^2} dx;$$
  

$$m(f) = \int_G \frac{g(x)f(x)}{(detx)^2} dx \quad f \in K(GL(2;\mathbb{R});\mathbb{R}^4)$$
  

$$= \int_{\mathbb{R}^4} \frac{g(x_{11};x_{12};x_{21};x_{22})f(x_{11};x_{12};x_{21};x_{22})}{(x_{11}x_{22}-x_{12}x_{21})^2} dx_{11} dx_{12} dx_{21} dx_{22}.$$

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